# Simulating Random Walks on Graphs in the Streaming Model 

Ce Jin

Tsinghua University
ITCS 2019

## Problem Definition

Insertion-only graph streaming model
Let $G$ be the (directed or undirected) input graph with $n$ vertices.
The edges of $G$ come as an input stream $\left(e_{1}, e_{2}, \ldots, e_{m}\right)$.
A streaming algorithm must read the edges one by one in this order.

## Problem Definition

## Insertion-only graph streaming model

Let $G$ be the (directed or undirected) input graph with $n$ vertices.
The edges of $G$ come as an input stream $\left(e_{1}, e_{2}, \ldots, e_{m}\right)$.
A streaming algorithm must read the edges one by one in this order.

Random walk on graph
A sequence of vertices $\left(v_{0}, v_{1}, \ldots, v_{t}\right)$ starting from $v_{0}$. For $i=1,2, \ldots, t,\left(v_{i-1}, v_{i}\right)$ is a uniform random edge drawn from the edges adjacent to $v_{i-1}$.

## Problem Definition

## Insertion-only graph streaming model

Let $G$ be the (directed or undirected) input graph with $n$ vertices.
The edges of $G$ come as an input stream $\left(e_{1}, e_{2}, \ldots, e_{m}\right)$.
A streaming algorithm must read the edges one by one in this order.

Random walk on graph
A sequence of vertices $\left(v_{0}, v_{1}, \ldots, v_{t}\right)$ starting from $v_{0}$. For $i=1,2, \ldots, t,\left(v_{i-1}, v_{i}\right)$ is a uniform random edge drawn from the edges adjacent to $v_{i-1}$.

Our problem: Simulating a $t$-step random walk
A starting vertex $v_{0}$ is given at the end of the input stream.
The streaming algorithm outputs a random sequence ( $v_{0}, v_{1}, \ldots, v_{t}$ ).
The $\ell_{1}$ distance between the output distribution and the distribution of $t$-step random walks is less than $\varepsilon$.

## A simple algorithm

## Reservoir Sampling

Given a stream of elements as input, one can uniformly sample $m$ elements from them using $O(m)$ space.

## A simple algorithm

## Reservoir Sampling

Given a stream of elements as input, one can uniformly sample $m$ elements from them using $O(m)$ space.

For every vertex $u$, store $t$ independent samples $v_{u, 1}, v_{u, 2}, \ldots, v_{u, t}$ of $u$ 's neighbors.

## A simple algorithm

## Reservoir Sampling

Given a stream of elements as input, one can uniformly sample $m$ elements from them using $O(m)$ space.

For every vertex $u$, store $t$ independent samples $v_{u, 1}, v_{u, 2}, \ldots, v_{u, t}$ of $u$ 's neighbors.
Perform a $t$-step random walk using these samples. After visiting $u$ for the $i$-th time, go to $v_{u, i}$ in the next step.

## A simple algorithm

## Reservoir Sampling

Given a stream of elements as input, one can uniformly sample $m$ elements from them using $O(m)$ space.

For every vertex $u$, store $t$ independent samples $v_{u, 1}, v_{u, 2}, \ldots, v_{u, t}$ of $u$ 's neighbors.
Perform a $t$-step random walk using these samples. After visiting $u$ for the $i$-th time, go to $v_{u, i}$ in the next step.
$O(n t)$ words of space. Perfect simulation $(\varepsilon=0)$

## A simple algorithm

## Reservoir Sampling

Given a stream of elements as input, one can uniformly sample $m$ elements from them using $O(m)$ space.

For every vertex $u$, store $t$ independent samples $v_{u, 1}, v_{u, 2}, \ldots, v_{u, t}$ of $u$ 's neighbors.
Perform a $t$-step random walk using these samples. After visiting $u$ for the $i$-th time, go to $v_{u, i}$ in the next step.
$O(n t)$ words of space. Perfect simulation $(\varepsilon=0)$

## Main questions

Can we do better (when small error $\varepsilon>0$ is allowed)?
Can we prove space lower bounds?

## Related work

In the multi-pass streaming model: Algorithm using $O(n)$ space and $O(\sqrt{t})$ passes. [Das Sarma, Gollapudi, Panigrahy, 2011]

## Related work

In the multi-pass streaming model: Algorithm using $O(n)$ space and $O(\sqrt{t})$ passes. [Das Sarma, Gollapudi, Panigrahy, 2011] Applications to estimating the page-rank vector, mixing time and conductance of graphs.

## Related work

In the multi-pass streaming model: Algorithm using $O(n)$ space and $O(\sqrt{t})$ passes. [Das Sarma, Gollapudi, Panigrahy, 2011] Applications to estimating the page-rank vector, mixing time and conductance of graphs.

Our study: What can we do in the single-pass streaming model?

## Results

- On a directed graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n t \log (n / t))$ bits of memory. (for $t \leq n / 2$ )


## Results

- On a directed graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n t \log (n / t))$ bits of memory. (for $t \leq n / 2$ )
- On an undirected graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n \sqrt{t})$ bits of memory. (for $t=O\left(n^{2}\right)$ )


## Results

- On a directed graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n t \log (n / t))$ bits of memory. (for $t \leq n / 2$ )
- On an undirected graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n \sqrt{t})$ bits of memory. (for $t=O\left(n^{2}\right)$ )
- On an undirected graph, we can simulate a $t$-step random walk using $O(n \sqrt{t})$ words of memory, with error $\varepsilon \leq 2^{-\Omega(\sqrt{t})}$.


## Results

- On a directed graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n t \log (n / t))$ bits of memory. (for $t \leq n / 2$ )
- On an undirected graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n \sqrt{t})$ bits of memory. (for $t=O\left(n^{2}\right)$ )
- On an undirected graph, we can simulate a $t$-step random walk using $O(n \sqrt{t})$ words of memory, with error $\varepsilon \leq 2^{-\Omega(\sqrt{t})}$.
- For smaller $\varepsilon$, we use $O\left(n\left(\sqrt{t}+\frac{\log \varepsilon^{-1}}{\log \log \varepsilon^{-1}}\right)\right)$ words of memory.


## Results

- On a directed graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n t \log (n / t))$ bits of memory. (for $t \leq n / 2$ )
- On an undirected graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n \sqrt{t})$ bits of memory. (for $t=O\left(n^{2}\right)$ )
- On an undirected graph, we can simulate a $t$-step random walk using $O(n \sqrt{t})$ words of memory, with error $\varepsilon \leq 2^{-\Omega(\sqrt{t})}$.
- For smaller $\varepsilon$, we use $O\left(n\left(\sqrt{t}+\frac{\log \varepsilon^{-1}}{\log \log \varepsilon^{-1}}\right)\right)$ words of memory.


## Results

- On a directed graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n t \log (n / t))$ bits of memory. (for $t \leq n / 2$ )
- On an undirected graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n \sqrt{t})$ bits of memory. (for $t=O\left(n^{2}\right)$ )
- On an undirected graph, we can simulate a $t$-step random walk using $O(n \sqrt{t})$ words of memory, with error $\varepsilon \leq 2^{-\Omega(\sqrt{t})}$.
- For smaller $\varepsilon$, we use $O\left(n\left(\sqrt{t}+\frac{\log \varepsilon^{-1}}{\log \log \varepsilon^{-1}}\right)\right)$ words of memory.

Nearly matching space lower bounds \& upper bounds for both directed/undirected settings!

## Results

- On a directed graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n t \log (n / t))$ bits of memory. (for $t \leq n / 2$ )
- On an undirected graph, simulating a $t$-step random walk with error $\varepsilon \leq 1 / 3$ requires $\Omega(n \sqrt{t})$ bits of memory. (for $t=O\left(n^{2}\right)$ )
- On an undirected graph, we can simulate a $t$-step random walk using $O(n \sqrt{t})$ words of memory, with error $\varepsilon \leq 2^{-\Omega(\sqrt{t})}$.
- For smaller $\varepsilon$, we use $O\left(n\left(\sqrt{t}+\frac{\log \varepsilon^{-1}}{\log \log \varepsilon^{-1}}\right)\right)$ words of memory.

Nearly matching space lower bounds \& upper bounds for both directed/undirected settings!

## Space lower bound for undirected graphs

We show a reduction from the INDEX problem.

## INDEX problem

Alice has an $n$-bit vector $X \in\{0,1\}^{n}$ and Bob has an index $i \in[n]$. Alice sends a message to Bob, and then Bob should output the bit $X_{i}$.

INDEX lower bound [Miltersen, Nisan, Safra, Wigderson, 1998]
For any constant $1 / 2<c \leq 1$, solving the INDEX problem with success probability $c$ requires sending $\Omega(n)$ bits.

## Space lower bound for undirected graphs

We show a reduction from the INDEX problem.

## INDEX problem

Alice has an $n$-bit vector $X \in\{0,1\}^{n}$ and Bob has an index $i \in[n]$. Alice sends a message to Bob, and then Bob should output the bit $X_{i}$.

INDEX lower bound [Miltersen, Nisan, Safra, Wigderson, 1998]
For any constant $1 / 2<c \leq 1$, solving the INDEX problem with success probability $c$ requires sending $\Omega(n)$ bits.

## INDEX protocol

Alice creates a graph consisting of $\frac{n}{\sqrt{t}}$ disjoint groups. Each group is a bipartite graph with $\sqrt{t}$ vertices on each side.

## INDEX protocol

Alice creates a graph consisting of $\frac{n}{\sqrt{t}}$ disjoint groups. Each group is a bipartite graph with $\sqrt{t}$ vertices on each side.
By inserting edges into every groups, she can encode $\frac{n}{\sqrt{t}} \times \sqrt{t} \times \sqrt{t}=n \sqrt{t}$ bits of information.




## INDEX protocol

Alice creates a graph consisting of $\frac{n}{\sqrt{t}}$ disjoint groups. Each group is a bipartite graph with $\sqrt{t}$ vertices on each side.
By inserting edges into every groups, she can encode $\frac{n}{\sqrt{t}} \times \sqrt{t} \times \sqrt{t}=n \sqrt{t}$ bits of information.




Bob wants to see whether edge $(a, b)$ exists.

## INDEX protocol

Alice creates a graph consisting of $\frac{n}{\sqrt{t}}$ disjoint groups. Each group is a bipartite graph with $\sqrt{t}$ vertices on each side.
By inserting edges into every groups, she can encode $\frac{n}{\sqrt{t}} \times \sqrt{t} \times \sqrt{t}=n \sqrt{t}$ bits of information.



Bob wants to see whether edge $(a, b)$ exists.
Alice sends the memory of the streaming algorithm to Bob. Bob adds $\sqrt{t}$ vertices and connect each of them to every vertex in a's side.

## Space lower bound for undirected graphs



Bob wants to see whether edge $(a, b)$ exists. He adds $\sqrt{t}$ vertices and connects each of them to every vertex in a's side.

- Starting from a Bob's vertex, go to a w.p. $\frac{1}{\sqrt{t}}$, then go to $b$ w.p. $\Theta\left(\frac{1}{\sqrt{t}}\right)$


## Space lower bound for undirected graphs




Bob wants to see whether edge $(a, b)$ exists. He adds $\sqrt{t}$ vertices and connects each of them to every vertex in a's side.

- Starting from a Bob's vertex, go to a w.p. $\frac{1}{\sqrt{t}}$, then go to $b$ w.p. $\Theta\left(\frac{1}{\sqrt{t}}\right)$
- visit a Bob's vertex every $O(1)$ steps with good probability


## Space lower bound for undirected graphs




Bob wants to see whether edge $(a, b)$ exists. He adds $\sqrt{t}$ vertices and connects each of them to every vertex in a's side.

- Starting from a Bob's vertex, go to a w.p. $\frac{1}{\sqrt{t}}$, then go to $b$ w.p. $\Theta\left(\frac{1}{\sqrt{t}}\right)$
- visit a Bob's vertex every $O(1)$ steps with good probability


## Space lower bound for undirected graphs




Bob wants to see whether edge $(a, b)$ exists. He adds $\sqrt{t}$ vertices and connects each of them to every vertex in a's side.

- Starting from a Bob's vertex, go to a w.p. $\frac{1}{\sqrt{t}}$, then go to $b$ w.p. $\Theta\left(\frac{1}{\sqrt{t}}\right)$
- visit a Bob's vertex every $O(1)$ steps with good probability

Edge $(a, b)$ is likely to be visited (if exists) after $O(t)$ steps. So bob can tell whether $(a, b)$ exists by simulating the generated $O(t)$-step random walk.

## Space lower bound for undirected graphs




Bob wants to see whether edge $(a, b)$ exists. He adds $\sqrt{t}$ vertices and connects each of them to every vertex in a's side.

- Starting from a Bob's vertex, go to a w.p. $\frac{1}{\sqrt{t}}$, then go to $b$ w.p. $\Theta\left(\frac{1}{\sqrt{t}}\right)$
- visit a Bob's vertex every $O(1)$ steps with good probability

Edge $(a, b)$ is likely to be visited (if exists) after $O(t)$ steps. So bob can tell whether $(a, b)$ exists by simulating the generated $O(t)$-step random walk.
By INDEX lower bound, we need $\Omega(n \sqrt{t})$ bits of space.

## Algorithm for undirected graphs

(For now we assume there are no multiple edges or self-loops)

- Small vertices: degree $\leq C$
- Big vertices: degree $>C$
for some parameter $C \approx \sqrt{t}$.


## Algorithm for undirected graphs

(For now we assume there are no multiple edges or self-loops)

- Small vertices: degree $\leq C$
- Big vertices: degree $>C$
for some parameter $C \approx \sqrt{t}$.
For every small vertex $u$ : store all neighbors of $u$.


## Algorithm for undirected graphs

(For now we assume there are no multiple edges or self-loops)

- Small vertices: degree $\leq C$
- Big vertices: degree $>C$
for some parameter $C \approx \sqrt{t}$.
For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.


## Algorithm for undirected graphs

(For now we assume there are no multiple edges or self-loops)

- Small vertices: degree $\leq C$
- Big vertices: degree $>C$
for some parameter $C \approx \sqrt{t}$.
For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors. Total space: $O(n \sqrt{t})$ words.


## Algorithm for undirected graphs using $O(n \sqrt{t})$ space

For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.
How to simulate a random walk? (Suppose we are now at vertex $u$ )

## Algorithm for undirected graphs using $O(n \sqrt{t})$ space

For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.

How to simulate a random walk? (Suppose we are now at vertex $u$ )

- If $u$ is small: simply pick a random neighbor $v$ as the next vertex


## Algorithm for undirected graphs using $O(n \sqrt{t})$ space

For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.

How to simulate a random walk? (Suppose we are now at vertex $u$ )

- If $u$ is small: simply pick a random neighbor $v$ as the next vertex
- If $u$ is big: flip a biased coin to decide if the next vertex will be big/small


## Algorithm for undirected graphs using $O(n \sqrt{t})$ space

For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.

How to simulate a random walk? (Suppose we are now at vertex $u$ )

- If $u$ is small: simply pick a random neighbor $v$ as the next vertex
- If $u$ is big: flip a biased coin to decide if the next vertex will be big/small
- next vertex is small: pick a random small neighbor (we know all of them!)


## Algorithm for undirected graphs using $O(n \sqrt{t})$ space

For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.

How to simulate a random walk? (Suppose we are now at vertex $u$ )

- If $u$ is small: simply pick a random neighbor $v$ as the next vertex
- If $u$ is big: flip a biased coin to decide if the next vertex will be big/small
- next vertex is small: pick a random small neighbor (we know all of them!)
- next vertex is big: have to consume a sample of $u$ 's big neighbor. (FAIL if all have been used)


## Algorithm for undirected graphs using $O(n \sqrt{t})$ space

For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.

How to simulate a random walk? (Suppose we are now at vertex $u$ )

- If $u$ is small: simply pick a random neighbor $v$ as the next vertex
- If $u$ is big: flip a biased coin to decide if the next vertex will be big/small
- next vertex is small: pick a random small neighbor (we know all of them!)
- next vertex is big: have to consume a sample of $u$ 's big neighbor. (FAIL if all have been used)


## Algorithm for undirected graphs using $O(n \sqrt{t})$ space

For every small vertex $u$ : store all neighbors of $u$.
For every big vertex $u$ : store $C$ independent samples of $u$ 's big neighbors.

How to simulate a random walk? (Suppose we are now at vertex $u$ )

- If $u$ is small: simply pick a random neighbor $v$ as the next vertex
- If $u$ is big: flip a biased coin to decide if the next vertex will be big/small
- next vertex is small: pick a random small neighbor (we know all of them!)
- next vertex is big: have to consume a sample of $u$ 's big neighbor. (FAIL if all have been used)

If we can make $\operatorname{Pr}[F A I L] \leq \varepsilon$, then our output distribution will be (2 2 )-close.

## Analysis of failure probability

We say a vertex $u$ fails, if the failure happens when we are at $u$.

## Analysis of failure probability

We say a vertex $u$ fails, if the failure happens when we are at $u$. $\operatorname{Pr}[$ FAIL $] \leq \sum_{u} \operatorname{Pr}[u$ fails $]$

## Analysis of failure probability

We say a vertex $u$ fails, if the failure happens when we are at $u$. $\operatorname{Pr}[$ FAIL $] \leq \sum_{u} \operatorname{Pr}[u$ fails $]$ $u$ fails only if the number of " $u \rightarrow$ Big" steps exceeds $C$.

## Analysis of failure probability

We say a vertex $u$ fails, if the failure happens when we are at $u$. $\operatorname{Pr}[$ FAIL $] \leq \sum_{u} \operatorname{Pr}[u$ fails $]$ $u$ fails only if the number of " $u \rightarrow$ Big" steps exceeds $C$.

$$
\operatorname{Pr}[u \text { fails }] \leq \sum_{\text {walk } w} \operatorname{Pr}[w] \cdot 1[w \text { has more than } C " u \rightarrow \text { Big" steps }]
$$

where $\operatorname{Pr}\left[\left(v_{0}, v_{1}, \ldots, v_{t}\right)\right]=\frac{1}{d\left(v_{0}\right) d\left(v_{1}\right) \ldots d\left(v_{t-1}\right)}$

$$
=\operatorname{Pr}\left[\left(v_{t}, \ldots, v_{0}\right)\right] \frac{d\left(v_{t}\right)}{d\left(v_{0}\right)}
$$

## Analysis of failure probability

We say a vertex $u$ fails, if the failure happens when we are at $u$. $\operatorname{Pr}[$ FAIL $] \leq \sum_{u} \operatorname{Pr}[u$ fails $]$
$u$ fails only if the number of " $u \rightarrow$ Big" steps exceeds $C$.

$$
\operatorname{Pr}[u \text { fails }] \leq \sum_{\text {walk } w} \operatorname{Pr}[w] \cdot 1[w \text { has more than } C " u \rightarrow \text { Big" steps }]
$$

where $\operatorname{Pr}\left[\left(v_{0}, v_{1}, \ldots, v_{t}\right)\right]=\frac{1}{d\left(v_{0}\right) d\left(v_{1}\right) \ldots d\left(v_{t-1}\right)}$

$$
=\operatorname{Pr}\left[\left(v_{t}, \ldots, v_{0}\right)\right] \frac{d\left(v_{t}\right)}{d\left(v_{0}\right)}
$$

The reversed walk $\left(v_{t}, \ldots, v_{0}\right)$ is still a walk (since the graph is undirected).

## Analysis of failure probability

We say a vertex $u$ fails, if the failure happens when we are at $u$. $\operatorname{Pr}[$ FAIL $] \leq \sum_{u} \operatorname{Pr}[u$ fails $]$
$u$ fails only if the number of " $u \rightarrow$ Big" steps exceeds $C$.

$$
\operatorname{Pr}[u \text { fails }] \leq \sum_{\text {walk } w} \operatorname{Pr}[w] \cdot 1[w \text { has more than } C " u \rightarrow \text { Big" steps }]
$$

where $\operatorname{Pr}\left[\left(v_{0}, v_{1}, \ldots, v_{t}\right)\right]=\frac{1}{d\left(v_{0}\right) d\left(v_{1}\right) \ldots d\left(v_{t-1}\right)}$

$$
=\operatorname{Pr}\left[\left(v_{t}, \ldots, v_{0}\right)\right] \frac{d\left(v_{t}\right)}{d\left(v_{0}\right)}
$$

The reversed walk $\left(v_{t}, \ldots, v_{0}\right)$ is still a walk (since the graph is undirected).
" $u \rightarrow$ Big" steps becomes "Big $\rightarrow u$ " steps!

## Algorithm for undirected graphs

Hence

$$
\operatorname{Pr}[u \text { fails }] \leq n \sum_{\text {walk } w} \operatorname{Pr}[w] \cdot 1[w \text { has more than } C \text { " } \operatorname{Big} \rightarrow u \text { " steps }]
$$

## Algorithm for undirected graphs

Hence

$$
\operatorname{Pr}[u \text { fails }] \leq n \sum_{\text {walk } w} \operatorname{Pr}[w] \cdot 1[w \text { has more than } C \text { " } \operatorname{Big} \rightarrow u \text { " steps }]
$$

Big vertex has degree $>C . \operatorname{Pr}\left[v_{i} \rightarrow v_{i+1}\right.$ is a " $\operatorname{Big} \rightarrow u$ " step $\left.\mid v_{i}\right]<1 / C$ In $t$ steps, "Big $\rightarrow u$ " happens $<t / C$ times in expectation (and it has concentration!)
Choosing $C=O\left(\sqrt{t} \log n \varepsilon^{-1}\right)$ makes $\operatorname{Pr}[$ FAIL $] \leq \sum_{u} \operatorname{Pr}[u$ fails $] \ll \varepsilon$.
(we can improve the log-factor using more careful analysis..)

## Dealing with multiple edges

When there are multiple edges,

$$
\operatorname{Pr}\left[v_{i} \rightarrow v_{i+1} \text { is a " } \mathrm{Big} \rightarrow u \text { " step } \mid v_{i}\right]<1 / C
$$

might not hold. (example: most of $v$ 's adjacent edges are connecting $u$ )

Fix: For each $u$, we use heavy-hitter algorithms to find those neighbors $v$ such that $\operatorname{Pr}\left[v_{i}=v \mid v_{i-1}=u\right]>1 / C$.

## Thank you!

